

July 25, 2014 (Fri)-1

Time	Hotel Nikko Kanazawa			
8:00	Registration desk open			
	Room A	Room B	Room C	Room D
			<b>Precision devices</b> Chairman: <i>(Prof. Keiichi Shirase)</i>	<b>CAD/CAM (1)</b> Chairman: <i>(Prof. Hideki Aoyama)</i>
9:00			<b>C21:</b> Development of a portable personal neck cooling system <i>Masanori Wada, Hiroshi Hosaka, Ken Sasaki, Kiyoshi Itao</i>	<b>D21:</b> Development of System to Predict and Minimize of Burrs in End-Milling <i>Sothea Kruey, Hideki Aoyama, Noriaki Sano</i>
9:20			<b>C22:</b> Study on asymmetrical tactile sensation of horizontal vibrating plane <i>Shohei Mishima</i>	<b>D22:</b> Ray-tracing simulation procedure for general isotropic inhomogeneous refractive-index media <i>Yohei Nishidate</i>
9:40			<b>C23:</b> Development of low power consumption vibration recording system <i>Xuchu Zhu, Fumito Yukawa, Hiroshi Hosaka</i>	<b>D23:</b> Investigation of Ball-Nose Endmilling Conditions Derived from Catalog Data Mining Based on Classified Inclination Angle of Machining Surface <i>Yui Sugaya, Hiroyuki Kodama, Toshiki Hirogaki, Eichi Aoyama, Keiji Ogawa</i>
10:00 10:20	Coffee break			

RoomA-C: Banquet Hall 3F, Room D: Function Room 3F (*La Grant Lumière*)

July 25, 2014 (Fri)-2

Time	Hotel Nikko Kanazawa			
	Room A	Room B	Room C	Room D
	<b>Advanced molding and forming</b> Chairman: <i>(Prof. Makoto Niikawa)</i>	<b>Measurement engineering (1)</b> Chairman: <i>(Prof. Yasuhiro Takaya)</i>	<b>Mechatronics (1)</b> Chairman: <i>(Prof. Masaya Takasaki)</i>	<b>CAD/CAM (2)</b> Chairman: <i>(Prof. Masatomo Inui)</i>

10:20	<p><b>A24:</b> Study on reduction of deformation of consolidated structure by layered manufacturing system -Optimization of laser scanning method- <i>Ryoji Ogura, Tatsuaki Furumoto, Akira Hosokawa, Tomohiro Koyano, Takashi Ueda</i></p>	<p><b>B24:</b> Visualization and analysis of a liquid-liquid two-phase flow using surface plasmon polaritons <i>Hiromichi Murata, Tatsuya Oku, Ryohei Seya, Miyu Ozaki, Ryoshu Furutani</i></p>	<p><b>C24:</b> Application of Electro-adhesive Rubber to Paper Handling System <i>Yuta Shimizu, Keita Matsuzawa, Yasuhiro Kakinuma, Tojiro Aoyama, Masaki Yoshino, Jun Aoto</i></p>	<p><b>D24:</b> Recognition and Reconstruction of Roadside Objects Based on Mobile Mapping Data <i>Kenta Fukano, Shougo Oguri, Hiroshi Masuda</i></p>
10:40	<p><b>A25:</b> Micro cyclic structuring on metal foil surface using Micro Form Rolling <i>Jun Tomita, Shohei Yamao, Minoru Ota, Kai Egashira, Keishi Yamaguchi, Yoshitaka Uehara</i></p>	<p><b>B25:</b> Investigation on the contact detection sensitivity of thermal contact sensor for surface defect inspections <i>Yuki Shimizu, Yuta Ohba, Wei Gao</i></p>	<p><b>C25:</b> Generation of a Procedure for Reaching a Specified Destination Based on Human Movement Data for a Humanoid Robot <i>Hiroyuki Ogata</i></p>	<p><b>D25:</b> Proposal of Machining Features for CAPP System for Complex Machining <i>Akira Ueno, Keiichi Nakamoto</i></p>
11:00	<p><b>A26:</b> Internal face finishing performance of cooling channel with face protuberance within molding die <i>Yoshiki Ochiai, Tatuaki Furumoto, Takashi Ueda, Akira Hosokawa, Tomohiro Koyano, Daiki Kusunoki</i></p>	<p><b>B26:</b> Development of 3D Measurement System using Single-shot Phase-shift Digital Holography <i>Yu Qiye</i></p>	<p><b>C26:</b> Development of Variable Stiffness Manipulator for Tactile Sensing for Mobility and Deformability Measurement <i>Daisuke Matsuura, Pavel Adodin, Yukio Takeda</i></p>	<p><b>D26:</b> Suggestion of 3D Direct Drawing Method by Microsoft Kinect <i>Kaoru Mitsuhashi, Ikuo Yoshida, Jin-Hua She, Yasuhiro Ohyama</i></p>
11:20	<p><b>A27:</b> Press Forming of CFRTP Sheet For High Cycle Production <i>Masaki Kimura</i></p>	<p><b>B27:</b> Large scale straightness evaluation using a gyro <i>Tatsuya Kume, Masanori Satoh, Tsuyoshi Suwada, Kazuro Furukawa, Eiki Okuyama</i></p>	<p><b>C27:</b> Impulse-driven Capsule for Medical Treatment - Wireless Implementation - <i>Takahiro Ito, Sunao Murakami, Teru Hayashi</i></p>	<p><b>D27:</b> Replicating Sharp Features of a Quadrilateral Mesh using the Corresponding Normal Vector <i>Yusuke Imai, Shogo Moriya, Hiroyuki Hiraoka, Hiroshi Kawaharada</i></p>
11:40	<p><b>A28:</b> Examination of processing conditions for sphere indentation finishing of MLA mold based on FEM analyses <i>Ryo Ishida, Yasunori Kobayashi, Haruhisa Sakamoto</i></p>	<p><b>B28:</b> On-machine form measurement of precision ceramics parts <i>So Ito, Takayuki Meguro, Daiki Matsuura, Yuki Shimizu, Wei Gao, Shigeru Adachi, Kyohei Omiya</i></p>	<p><b>C28:</b> Three-dimensional Slide-bending Formation of Metallic Foil by Using an Industrial Robot <i>Hiroshi Harada, Yuki Niiji, Kouhei Kawabe, Yasuo Marumo, Teruo Yamaguchi</i></p>	<p><b>D28:</b> Development of Process Planning System for Turning-Milling Center <i>Khusna Dwijayanti, Hideki Aoyama</i></p>
12:00 13:20	<b>Lunch</b>			

**RoomA-C: Banquet Hall 3F, Room D: Function Room 3F (La Grant Lumière )**

Time	Hotel Nikko Kanazawa			
	Room A	Room B	Room C	Room D
	<p><b>Machine tools (1)</b>                      Chairman:                      (Prof. Yasuhiro Kakinuma)</p>	<p><b>Measurement engineering (2)</b>                      Chairman:                      (Prof. Masato Okada)</p>	<p><b>Mechatronics (2)</b>                      Chairman:                      (Prof. Hiroaki Seki)</p>	<p><b>CAD/CAM (3)</b>                      Chairman:                      (Prof. Keiichi Nakamoto)</p>
13:20	<p><b>A29:</b>                      High speed cutting of Ti-6Al-4V -Effect of tool holder materials on tool wear-                      Tetsuya Tashiro, Junsuke Fujiwara, Kohei Kuroda</p>	<p><b>B29:</b>                      Profile measurement of an aspherical mirror by high-speed nanoprofiler using normal vector tracing method                      Yusuke Tokuta, Koji Usuki, Takuya Kojima, Kenya Okita, Kohei Okuda, Takao Kitayama, Motohiro Nakano, Yasuo Higashi, Ryota Kudo, Kazuya Yamamura, Katsuyoshi Endo</p>	<p><b>C29:</b>                      Vibration Control for High-speed Miniature Assembling by Adding Speed Pattern.                      Kyouhei Shinsen, Tohru Sasaki, Yusuke Ikemoto, Mitsuru Jindai</p>	<p><b>D29:</b>                      Data Conversion From Dexcel Model to B-reps Solid Model.                      Masatomo Inui</p>
13:40	<p><b>A30:</b>                      Investigation of Belag Formation Mechanisms on the Edge of Cutting Tools after Machining of Low-alloy and Medium-carbon Steel                      Kana Morishita, Kenichi Inoue, Shigekazu Morito, Takuya Ohba</p>	<p><b>B30:</b>                      Stereo-camera system with digital image correlation method for accurate measurement of position and orientation of a positioning stage                      Yusuke Horikawa, Hisao Kikuta, Tomoaki Noda, Akio Mizutani</p>	<p><b>C30:</b>                      Simulation of Remote-Controlled 6DOF Assembly using a 1DOF Haptic Device                      Shinji Shinogi, Ryoya Kamata, Ryosuke Tamura, Satoshi Niitsu, Ryo Shimano, Shinji Shinogi, Hiroshi Kawaharada, Hiroyuki Hiraoka</p>	<p><b>D30:</b>                      Segmentation, Dimension-Driven Deformation, and Quality Improvement of Tetrahedral Mesh Models for Finite Element Analysis                      Hiroki Maehama, Hiroaki Date, Satoshi Kanai</p>
14:00	<p><b>A31:</b>                      Effect of the Core-Rim Structure of Ti(C,N) Based Cermets on the Thermal Conductivity and Cutting Performance                      Takato Yamanishi, Masato Michiuchi, Keiich Tsuda</p>	<p><b>B31:</b>                      Evaluation of a cup-type Diamond Grinding Wheel Surface using Image Processing                      Akihiro Sakaguchi, Tomoyuki Kawashita, Shuji Matsuo</p>	<p><b>C31:</b>                      Development of a 1DOF Haptic Device for Remote-Controlled 6DOF Assembly - Feedback of Force and Control of Direction-                      Ryo Shimano, Ryoya Kamata, Ryosuke Tamura, Satoshi Niitsu, Shinji Shinogi, Hiroshi Kawaharada, Hiroyuki Hiraoka</p>	<p><b>D31:</b>                      Registration of Point Clouds of Large Scale Environments using Point Projection Images                      Hiroaki Date, Yusuke Matsuyama, Satoshi Kanai</p>
14:20	<p><b>A32:</b>                      Analysis of positional deviation caused by position-dependent disturbances in ball screw drive                      Daisuke Kono, Atsushi Matsubara, Takeki Shirai, Kaoru Hoshide, Tetsuya Miura, Tsutomu Togashi</p>	<p><b>B32:</b>                      Measurement of Volumetric Accuracy of Three-axis Machine Tools using Open-loop Laser Tracker                      Keishi Nagae</p>	<p><b>C32:</b>                      Remote-Controlled 6DOF Assembly using a 1DOF Haptic Device with Virtual Coordinate System                      Ryosuke Tamura, Ryoya Kamata, Satoshi Niitsu, Shinji Sinogi, Ryo Shimano, Hiroshi Kawaharada, Hiroyuki Hiraoka</p>	<p><b>D32:</b>                      Point-Based Collision Detection for Planning Maintenance and Reorganization Tasks for Manufacturing Plants                      Takeru Niwa, Minako Hiraoka, Hiroshi Masuda</p>

14:20	<b>A33:</b> Development of Multi-Axis Micro Sawing Machine for Free-Form Curves Cutting Using Flexible Circular Saw <i>Yohei Yamada, Hiroyuki Sasahara</i>	<b>B33:</b> An R-test analysis software for error calibration of five-axis machine tools <i>Soichi Ibaraki, Yu Nagai, Hisashi Otsubo, Yasutaka Sakai, Shigeki Morimoto</i>	<b>C33:</b> Development of remote-controlled 6DOF Assembly using a 1DOF haptic device - Judgment of the constraint state using a 6-axis force sensor- <i>Satoshi Niitsu, Ryoya Kamata, Ryosuke Tamura, Ryo Shimano, Shinji Shinogi, Hiroshi Kawaharada, Hiroyuki Hiraoka</i>	<b>D33:</b> Segment Extraction from Point Cloud Using a Panoramic Layered Range Image <i>Masafumi Nakagawa, Kounosuke Kataoka</i>
15:00 15:20	<b>Coffee break</b>			

**RoomA-C: Banquet Hall 3F, Room D: Function Room 3F (La Grant Lumière )**

July 25, 2014 (Fri)-4

Time	Hotel Nikko Kanazawa			
	Room A	Room B	Room C	Room D
	<b>Machine tools (2)</b> <i>Chairman:</i> <i>(Prof. Daisuke Kono)</i>	<b>Measurement engineering (3)</b> <i>Chairman:</i> <i>(Prof. Soichi Ibaraki)</i>	<b>Mechatronics (3)</b> <i>Chairman:</i> <i>(Prof. Hiroyuki Hiraoka)</i>	<b>Medical devices</b> <i>Chairman:</i> <i>(Prof. Jiro Sakamoto)</i>
15:20	<b>A34:</b> Performance of High-Speed Precision Air-Bearing Spindle with Active Aerodynamic Bearing <i>Hiroshi Mizumoto, Yoichi Tazoe, Tomohiro Hirose, Katsuhiko Atoji</i>	<b>B34:</b> Self calibration of 2D parallel mechanism with three degree of freedom <i>Satoshi Yokouchi, Hiroshi Takazawa, Takahiro Tanaka, Miyu Ozaki, Ryoshu Furutani</i>	<b>C34:</b> Vibration Suppression using Filtered Velocity Reference for Flexible Structure <i>Hiroshi Hamamatsu, Yasunobu Hitaka, Seiji Furuno, Takayuki Matsuo</i>	<b>D34:</b> An investigation of cell adhesion and growth on micro/nano-scale structured surface <i>Iwori Takeda, Masato Kawanabe, Ryo Inoue, Arata Kaneko</i>
15:40	<b>A35:</b> Study on Cutting Mechanism and Cutting Performance of Inclined Surface with Radius End Mill <i>Hiroyasu Iwabe, Kyouhei Kikuchi, Masanori Futakawa, Yusaku Kazama</i>	<b>B35:</b> Development of three-dimensional measuring system for screen-printing process <i>Shinya Yoshida, Yusuke Ogiso, Akihiro Mizutani</i>	<b>C35:</b> Improve contouring accuracy by integral sliding mode controllers designed by robust digital control <i>Xue-Cheng Xi, Wansheng Zhao, You Wang</i>	<b>D35:</b> A Study on Orthodontics Simulation Method Based on Periodontal Ligament Stress <i>Jiro Sakamoto, Shinya Kokubo</i>

